

# NAG Toolbox for MATLAB

## e04yc

### 1 Purpose

e04yc returns estimates of elements of the variance-covariance matrix of the estimated regression coefficients for a nonlinear least-squares problem. The estimates are derived from the Jacobian of the function  $f(x)$  at the solution.

This function may be used following any one of the nonlinear least-squares functions e04fc, e04fy, e04gb, e04gy, e04gd, e04gz, e04he or e04hy.

### 2 Syntax

```
[v, cj, ifail] = e04yc(job, m, fsumsq, s, v, 'n', n)
```

### 3 Description

e04yc is intended for use when the nonlinear least-squares function,  $F(x) = f^T(x)f(x)$ , represents the goodness-of-fit of a nonlinear model to observed data. The function assumes that the Hessian of  $F(x)$ , at the solution, can be adequately approximated by  $2J^T J$ , where  $J$  is the Jacobian of  $f(x)$  at the solution. The estimated variance-covariance matrix  $C$  is then given by

$$C = \sigma^2 (J^T J)^{-1}, \quad J^T J \text{ nonsingular,}$$

where  $\sigma^2$  is the estimated variance of the residual at the solution,  $\bar{x}$ , given by

$$\sigma^2 = \frac{F(\bar{x})}{m - n},$$

$m$  being the number of observations and  $n$  the number of variables.

The diagonal elements of  $C$  are estimates of the variances of the estimated regression coefficients. See the E04 Chapter Introduction, Bard 1974 and Wolberg 1967 for further information on the use of  $C$ .

When  $J^T J$  is singular then  $C$  is taken to be

$$C = \sigma^2 (J^T J)^\dagger,$$

where  $(J^T J)^\dagger$  is the pseudo-inverse of  $J^T J$ , and

$$\sigma^2 = \frac{F(\bar{x})}{m - k}, \quad k = \text{rank}(J)$$

but in this case the parameter **ifail** is returned as nonzero as a warning to you that  $J$  has linear dependencies in its columns. The assumed rank of  $J$  can be obtained from **ifail**.

The function can be used to find either the diagonal elements of  $C$ , or the elements of the  $j$ th column of  $C$ , or the whole of  $C$ .

e04yc must be preceded by one of the nonlinear least-squares functions mentioned in Section 1, and requires the parameters **fsumsq**, **s** and **v** to be supplied by those functions (e.g., see e04fc). **fsumsq** is the residual sum of squares  $F(\bar{x})$  and **s** and **v** contain the singular values and right singular vectors respectively in the singular value decomposition of  $J$ . **s** and **v** are returned directly by the comprehensive functions e04fc, e04gb, e04gd and e04he, but are returned as part of the workspace parameter **w** (from one of the easy-to-use functions). In the case of e04fy, **s** starts at **w(NS)**, where

$$NS = 6 \times \mathbf{n} + 2 \times \mathbf{m} + \mathbf{m} \times \mathbf{n} + 1 + \max(1, \mathbf{n} \times (\mathbf{n} - 1)/2)$$

and in the cases of the remaining easy-to-use functions, **s** starts at **w(NS)**, where

$$NS = 7 \times \mathbf{n} + 2 \times \mathbf{m} + \mathbf{m} \times \mathbf{n} + \mathbf{n} \times (\mathbf{n} + 1)/2 + 1 + \max(1, \mathbf{n} \times (\mathbf{n} - 1)/2).$$

The parameter **v** starts immediately following the elements of **s**, so that **v** starts at **w(NV)**, where

$$NV = NS + \mathbf{n}.$$

For all the easy-to-use functions the parameter **ldv** must be supplied as **n**. Thus a call to e04yc following e04fy can be illustrated as

```
.
.
.
[x, fsumsq, user, ifail] = e04fy(m, lsfun1, x);
.
.
.
ns = 6*n + 2*m + m*n + 1 + max((1, (n*(n-1))/2);
nv = ns + n;
[v, cj, ifail] = e04yc(job, m, fsumsq, w(ns:nv-1), w(nv:numel(w)));
```

where the parameters **m**, **n**, **fsumsq** and the  $(n + n^2)$  elements **w(NS)**, **w(NS + 1)**, ..., **w(NV + n - 1)** must not be altered between the calls to e04fy and e04yc. The above illustration also holds for a call to e04yc following a call to one of e04gy, e04gz or e04hy, except that **NS** must be computed as

$$NS = 7 \times \mathbf{n} + 2 \times \mathbf{m} + \mathbf{m} \times \mathbf{n} + (\mathbf{n} \times (\mathbf{n} + 1))/2 + 1 + \max((1, \mathbf{n} \times (\mathbf{n} - 1))/2).$$

## 4 References

Bard Y 1974 *Nonlinear Parameter Estimation* Academic Press

Wolberg J R 1967 *Prediction Analysis* Van Nostrand

## 5 Parameters

### 5.1 Compulsory Input Parameters

1: **job** – int32 scalar

Which elements of **C** are returned as follows:

**job** = -1

The  $n$  by  $n$  symmetric matrix **C** is returned.

**job** = 0

The diagonal elements of **C** are returned.

**job** > 0

The elements of column **job** of **C** are returned.

*Constraint:*  $-1 \leq \mathbf{job} \leq \mathbf{n}$ .

2: **m** – int32 scalar

The number  $m$  of observations (residuals  $f_i(x)$ ).

*Constraint:*  $\mathbf{m} \geq \mathbf{n}$ .

3: **fsumsq** – double scalar

The sum of squares of the residuals,  $F(\bar{x})$ , at the solution  $\bar{x}$ , as returned by the nonlinear least-squares function.

*Constraint:* **fsumsq**  $\geq$  0.0.

4: **s(n)** – double array

The  $n$  singular values of the Jacobian as returned by the nonlinear least-squares function. See Section 3 for information on supplying **s** following one of the easy-to-use functions.

5: **v(ldv,n) – double array**

**ldv**, the first dimension of the array, must be at least if **job** = -1, **ldv** ≥ **n**.

The  $n$  by  $n$  right-hand orthogonal matrix (the right singular vectors) of  $J$  as returned by the nonlinear least-squares function. See Section 3 for information on supplying **v** following one of the easy-to-use functions.

**5.2 Optional Input Parameters**1: **n – int32 scalar**

*Default:* The dimension of the arrays **s**, **v**, **cj**. (An error is raised if these dimensions are not equal.)  
the number  $n$  of variables ( $x_j$ ).

*Constraint:*  $1 \leq \mathbf{n} \leq \mathbf{m}$ .

**5.3 Input Parameters Omitted from the MATLAB Interface**

**ldv**, **work**

**5.4 Output Parameters**1: **v(ldv,n) – double array**

If **job** ≥ 0, **v** is unchanged.

If **job** = -1, the leading  $n$  by  $n$  part of **v** contains the  $n$  by  $n$  matrix  $C$ . When e04yc is called with **job** = -1 following an easy-to-use function this means that  $C$  is returned, column by column, in the  $n^2$  elements of **w** given by **w**( $NV$ ), **w**( $NV + 1$ ), ..., **w**( $NV + n^2 - 1$ ). (See Section 3 for the definition of  $NV$ .)

2: **cj(n) – double array**

If **job** = 0, **cj** returns the  $n$  diagonal elements of  $C$ .

If **job** =  $j > 0$ , **cj** returns the  $n$  elements of the  $j$ th column of  $C$ .

If **job** = -1, **cj** is not referenced.

3: **ifail – int32 scalar**

0 unless the function detects an error (see Section 6).

**6 Error Indicators and Warnings**

**Note:** e04yc may return useful information for one or more of the following detected errors or warnings.

**ifail** = 1

On entry, **job** < -1,  
or **job** > **n**,  
or **n** < 1,  
or **m** < **n**,  
or **fsumsq** < 0.0,  
or **ldv** < **n**.

**ifail** = 2

The singular values are all zero, so that at the solution the Jacobian matrix  $J$  has rank 0.

**ifail** > 2

At the solution the Jacobian matrix contains linear, or near linear, dependencies amongst its columns. In this case the required elements of  $C$  have still been computed based upon  $J$  having an assumed rank given by (**ifail** = 2). The rank is computed by regarding singular values  $SV(j)$  that are not larger than  $10\epsilon \times SV(1)$  as zero, where  $\epsilon$  is the *machine precision* (see x02aj). If you expect near linear dependencies at the solution and are happy with this tolerance in determining rank you should call e04yc with **ifail** = 1 in order to prevent termination. It is then essential to test the value of **ifail** on exit from e04yc.

overflow

If overflow occurs then either an element of  $C$  is very large, or the singular values or singular vectors have been incorrectly supplied.

## 7 Accuracy

The computed elements of  $C$  will be the exact covariances corresponding to a closely neighbouring Jacobian matrix  $J$ .

## 8 Further Comments

When **job** = -1 the time taken by e04yc is approximately proportional to  $n^3$ . When **job** ≥ 0 the time taken by the function is approximately proportional to  $n^2$ .

## 9 Example

```

job = int32(0);
m = int32(15);
fsumsq = 0.00821487730657898;
s = [4.096503460740998;
     1.59495793805472;
     0.06125849312174952];
v = [0.9353959086918022, 0.3529512209498857, -0.02144597007884219;
     -0.2592284256717189, 0.6432345920936757, -0.7204511661853596;
     -0.2404893289241745, 0.6794664783225641, 0.6931739951192144];
[vOut, cj, ifail] = e04yc(job, m, fsumsq, s, v)

vOut =
    0.9354    0.3530   -0.0214
   -0.2592    0.6432   -0.7205
   -0.2405    0.6795    0.6932
cj =
    0.0002
    0.0948
    0.0878
ifail =
        0

```